pos\_y = (vel\_y\*t) - (0.5\*10\*(pow(t,2)));

pos\_x = vel\_x\*t;

Print(pos\_x, pos\_y)

Print(pos\_x) as jarak maksimal

t = t +1

True

False

Pos\_y >= 0 or t = 0

Var:

* vel\_x = 50 \* (cos(60\*PI/180));
* vel\_y = 50 \* sin(60\*PI/180);
* pos\_x = 0;
* pos\_y = 0;
* t = 0;

Define:

* PI = 3.13159264

**FINISH**

**START**